



Introduction to Empowerment with an application in control of electrical distribution grids

Silvan Faßbender, Jan Bollenbacher
supervised by

Prof. Dr. Waffenschmidt, Prof. Dr. Rhein

XXVII. Deutsch-Polnisches Wissenschaftliches Seminar, TH Köln

08. Juni 2016



Agenda

- Empowerment
 - Analogon
 - Principles and goal
 - Definition
- Control of electrical distribution grids
 - Voltage control by power factor adaption
 - Limits in the low-voltage grid
 - Application of Empowerment
- Conclusion and perspective





Empowerment



[1]





Principles and goal

- Main Principles [2]:
 - Local
 - Universal
 - Task-independent
- Heuristic:
'The state of the most perspectives of influence is the best'
- Quantify the amount of influence with the information theoretical entropy

Entropy



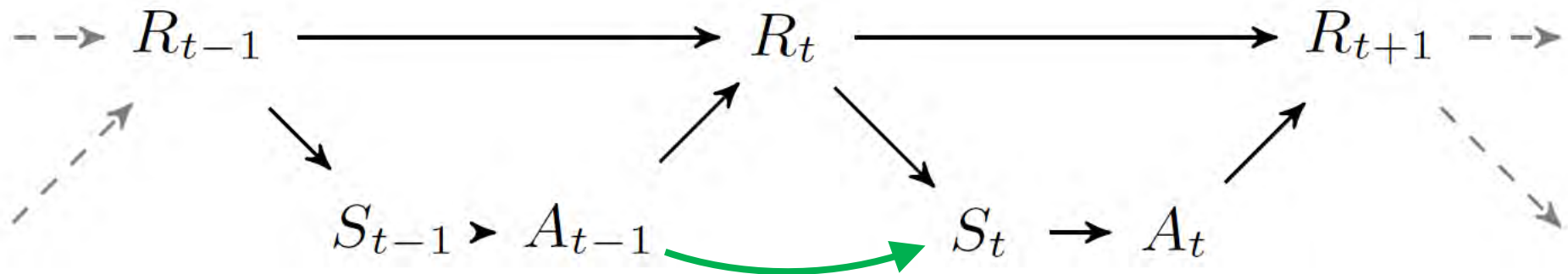
$$H = \log_2 2^N = N = 2 \text{ bits}$$



[3]

Interaction of agent and environment

- The agent performs a perception action loop with
 - Its own actuator A (sender)
 - The environment R (transmitter)
 - Its own sensor S (receiver)



[2]

Mutual information

$$H(S_s) = - \sum_{s' \in S_s} p(s'|s) \log_2 p(s'|s)$$

$$H(S_s | \mathcal{A}_s) = - \sum_{a \in \mathcal{A}_s} p(a) \sum_{s' \in S_s} p(s'|s, a) \log_2 p(s'|s, a)$$

$$I(S_s : \mathcal{A}_s) = H(S_s) - H(S_s | \mathcal{A}_s)$$

Legend of variables:

$I(S_s : \mathcal{A}_s)$	mutual information of the channel between sensor and actuator
$H(S_s)$	entropy of sensor set S_s
$H(S_s \mathcal{A}_s)$	conditional entropy of the sensor set S_s given actuator \mathcal{A}_s
\mathcal{A}_s	discrete random variable modeling selection of action
$p(\vec{a})$	distribution over \mathcal{A}_s (number-of-actions vector)
S_s	discrete random variable modeling occurrence of successor state given s
$p(s' s)$	distribution over S_s (number-of-sensor-output vector)
$p(s' s, a)$	transition probabilities (dynamics of the world)

[2]

Empowerment

$$\mathcal{E} = C(s) := \max_{p(\vec{a})} I(S_s : \mathcal{A}_s)$$

$$\mathcal{E} = \max_{p(\vec{a})} \sum_{s'} \sum_a p(a) p(s'|s, a) \log_2 \left\{ \frac{p(s'|s, a)}{\sum_{a'} p(s'|s, a') p(a')} \right\}$$

Legend of variables:

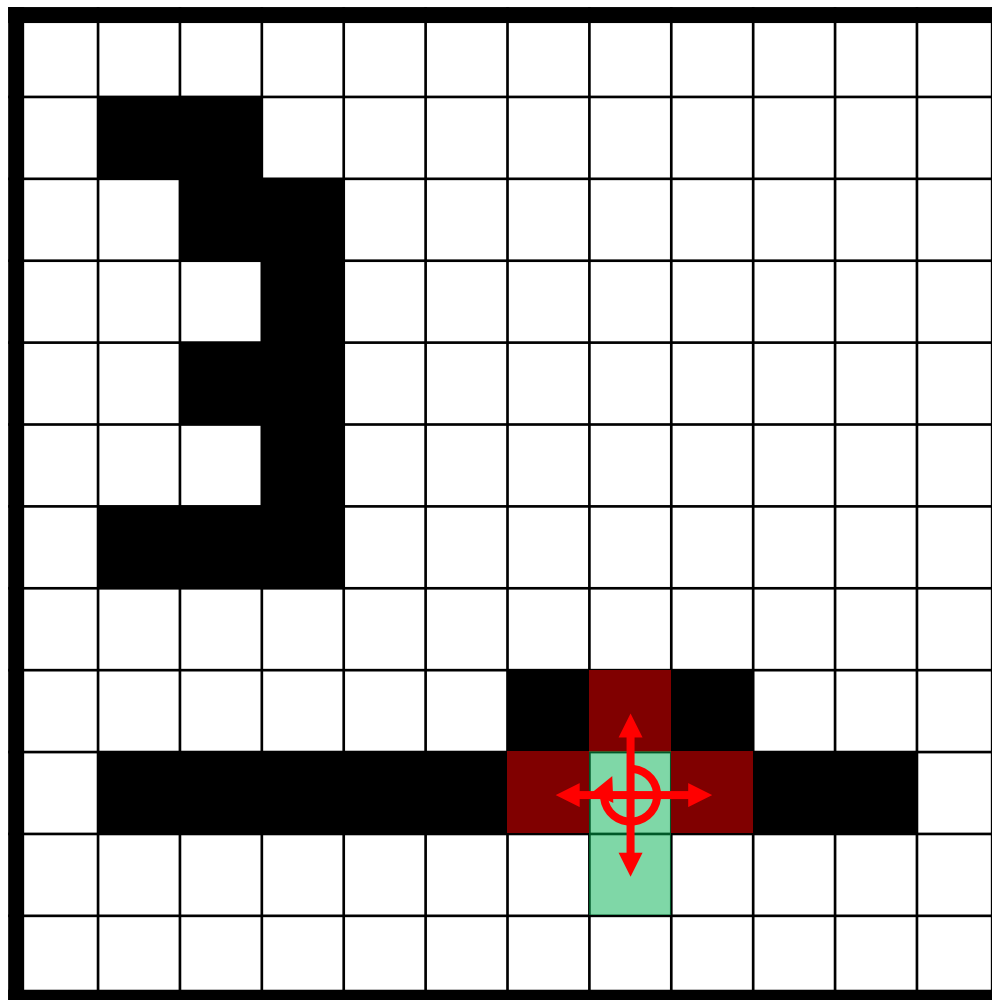
\mathcal{E}	Empowerment [bits]
$C(s)$	Channel capacity
$I(S_s : \mathcal{A}_s)$	mutual information of the channel between sensor and actuator
\mathcal{A}_s	discrete random variable modeling selection of action
$p(\vec{a})$	distribution over \mathcal{A}_s (number-of-actions vector)
S_s	discrete random variable modeling occurrence of successor state given s
$p(s' s, a)$	transition probabilities (dynamics of the world)

[2]



Grid world example

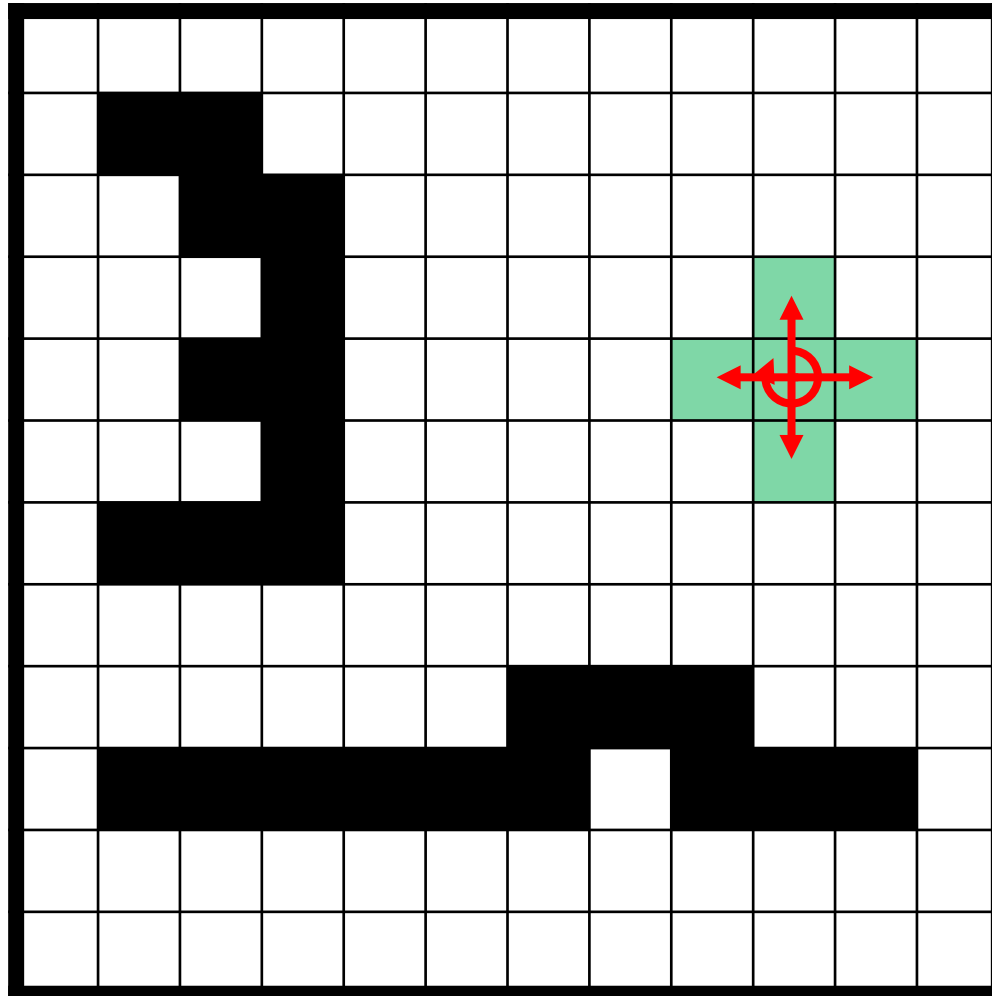
X ←
N ←
E ←
S ←
W ←



$$\mathcal{E} = \log_2 2 = 1$$

[4]

Grid world example



X ←
N ←
E ←
S ←
W ←

$$\mathcal{C} = \log_2 5 = 2.32$$

[4]

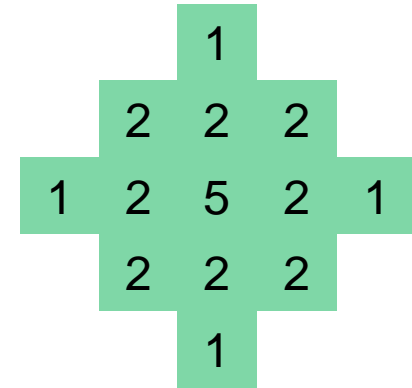
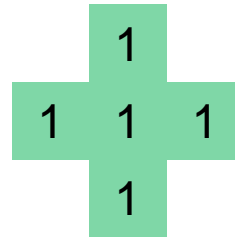


Application of Empowerment to Gridworld

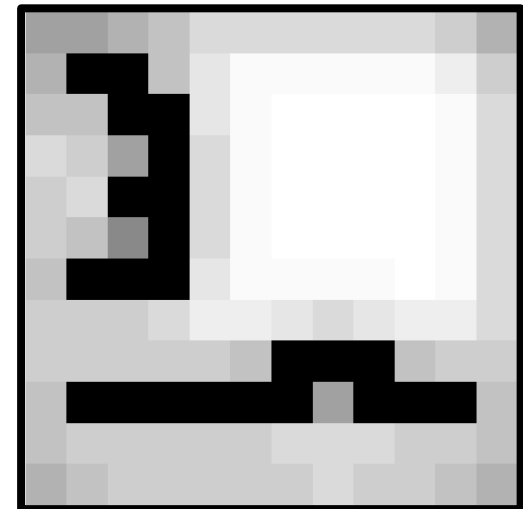
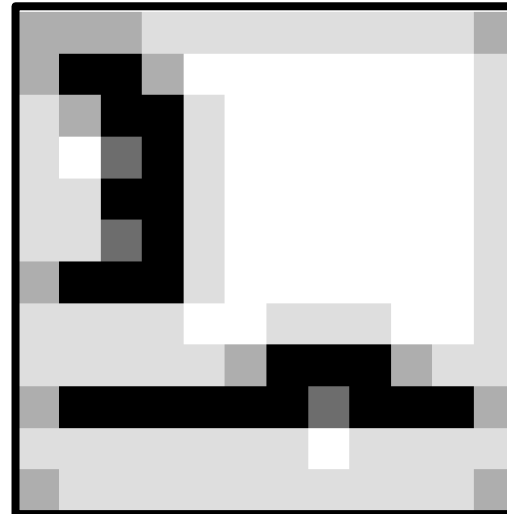
1-step- \mathcal{E}

2-step- \mathcal{E}

Number of possible paths achieving a particular cell



Empowerment-map



[min; max] of \mathcal{E}

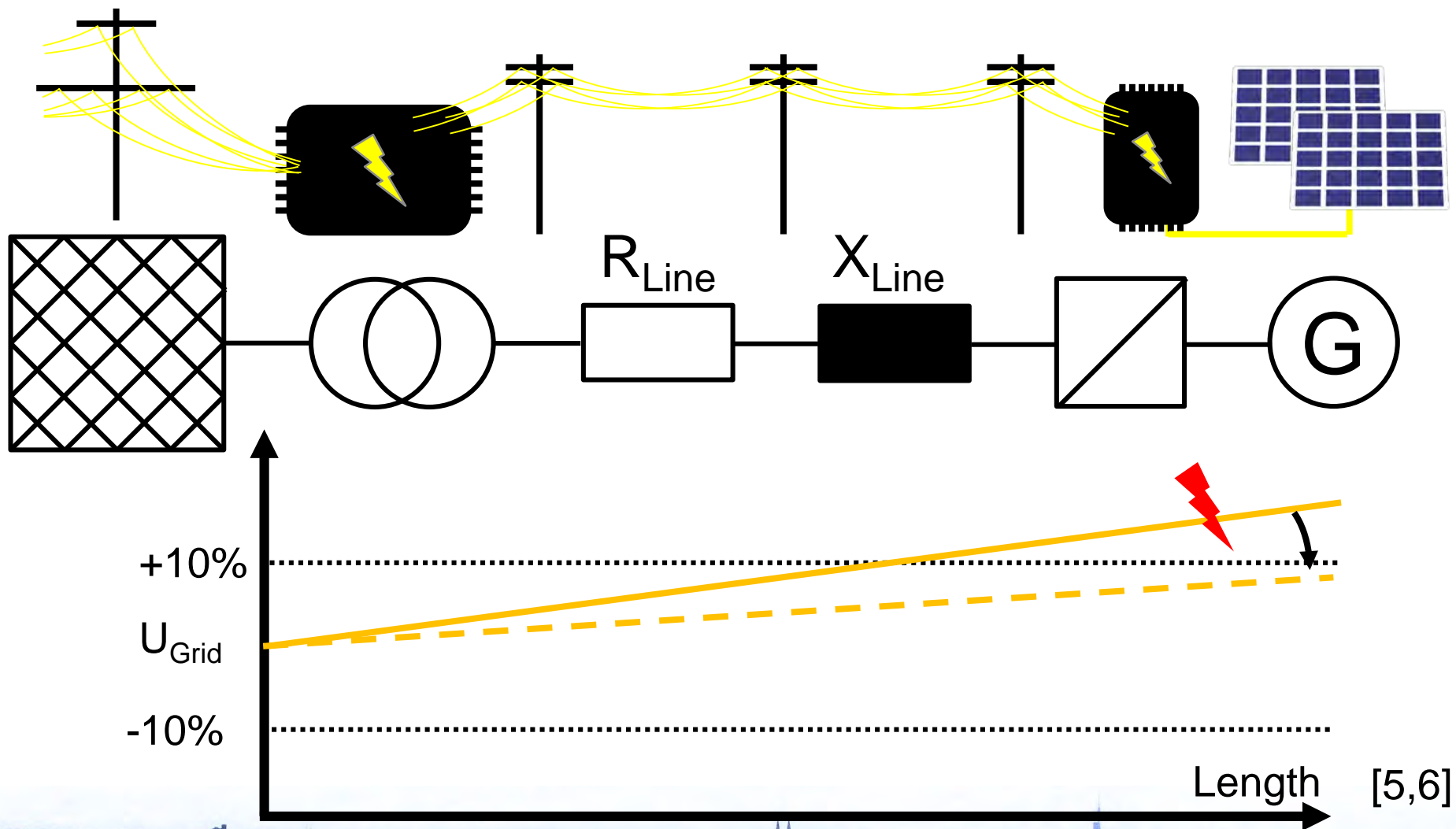
[1; 2,32]

[2; 3,70]

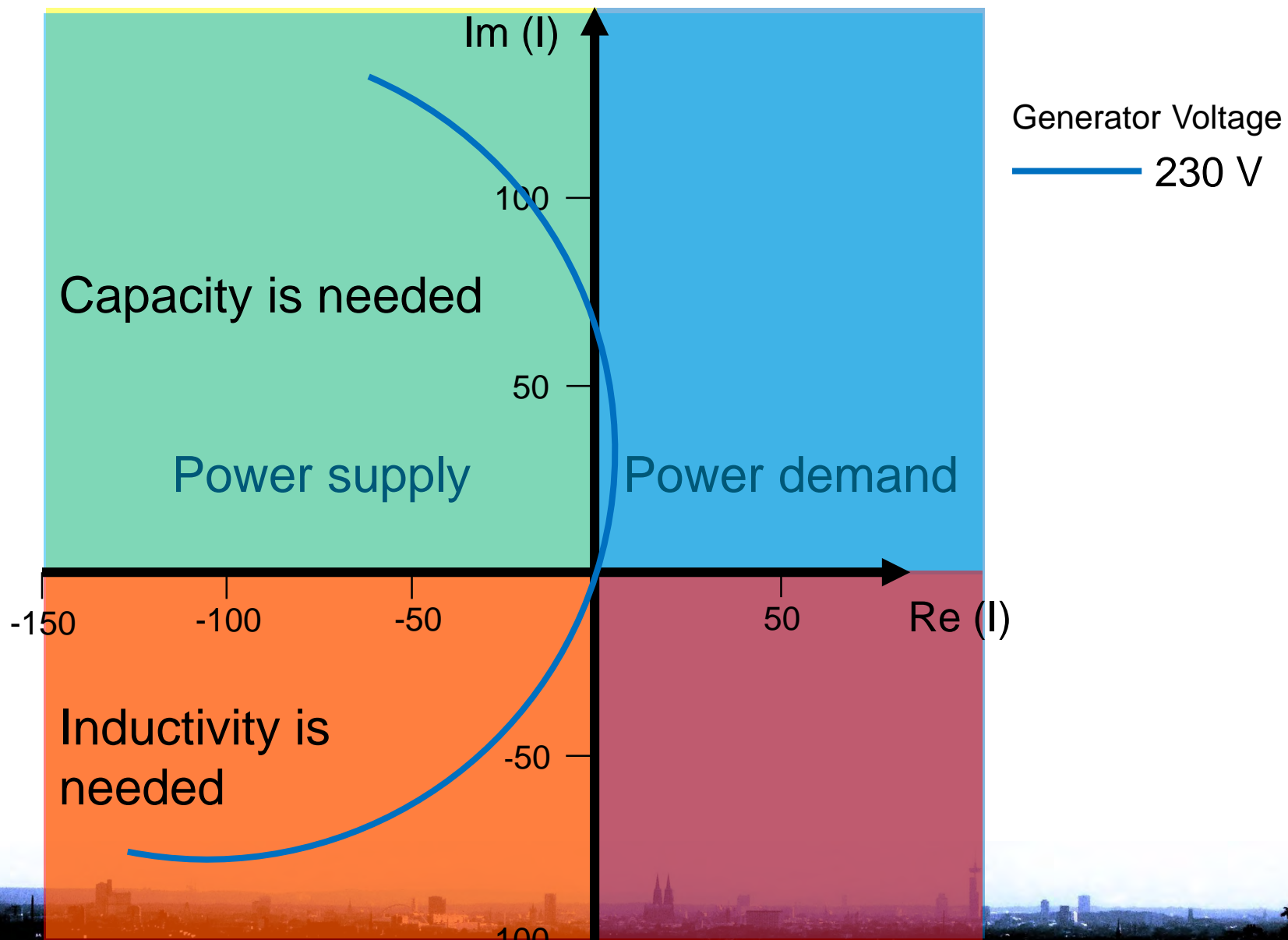
[4]



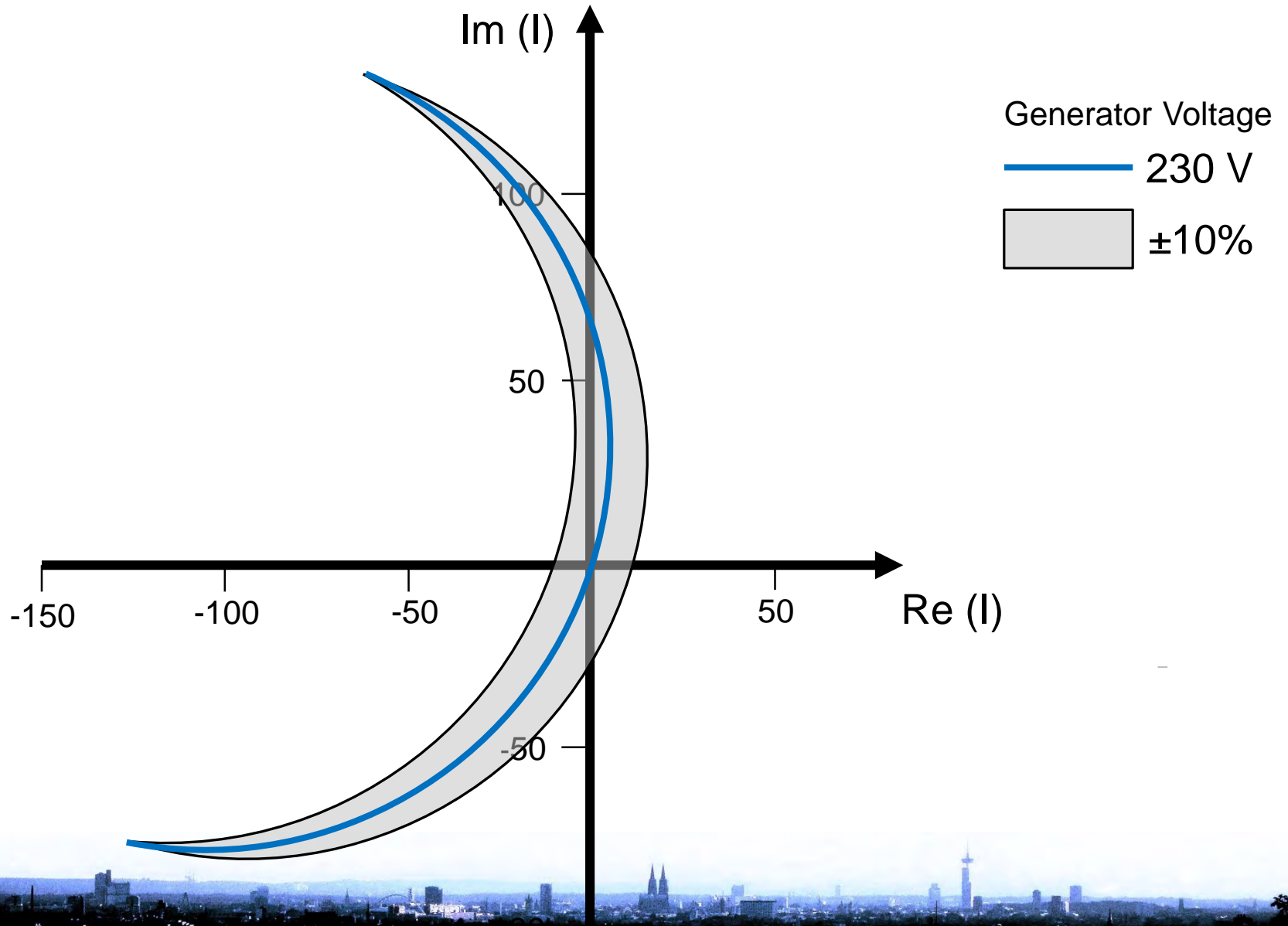
Control of electrical distribution grids



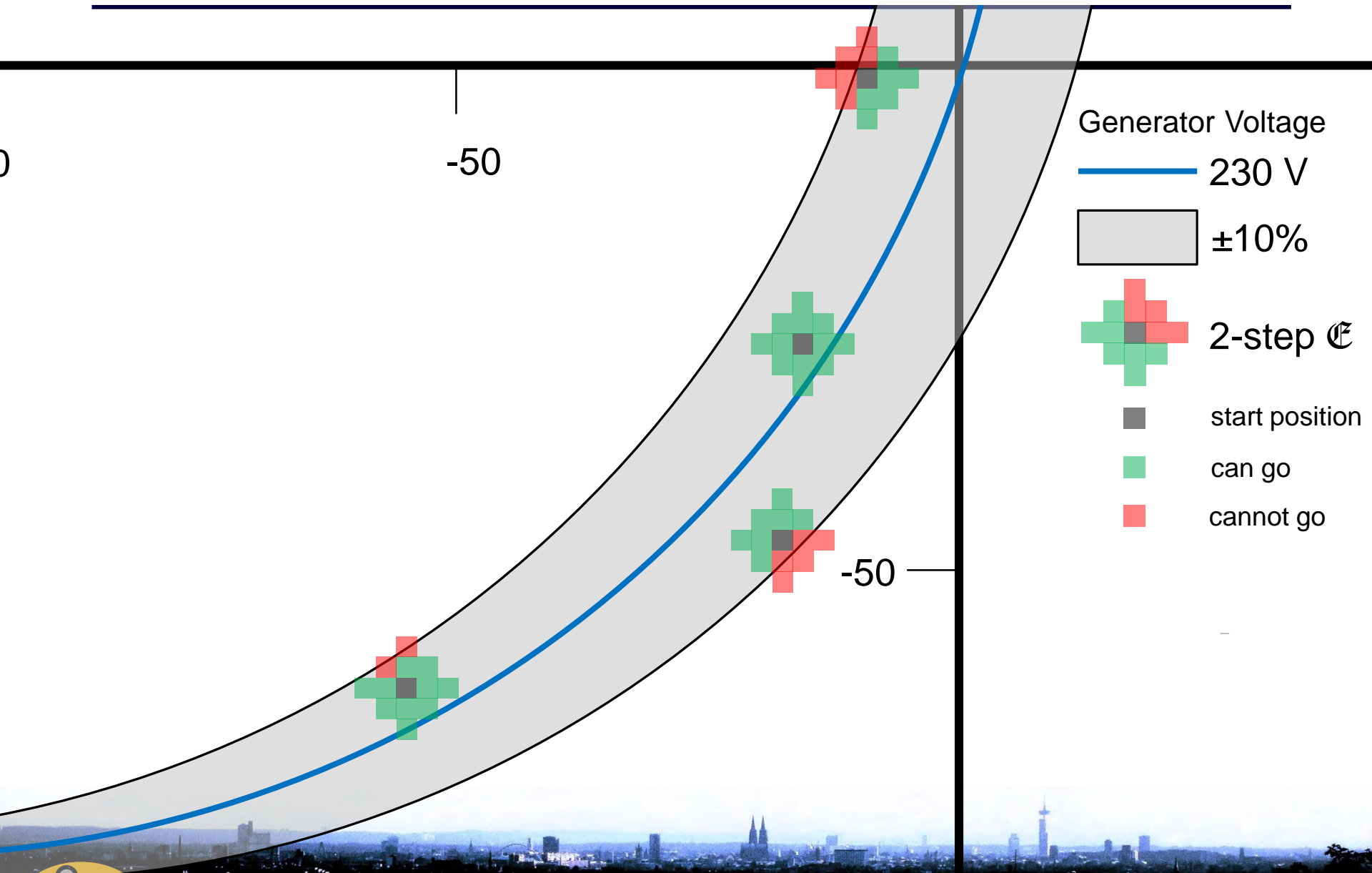
Power factor adaption



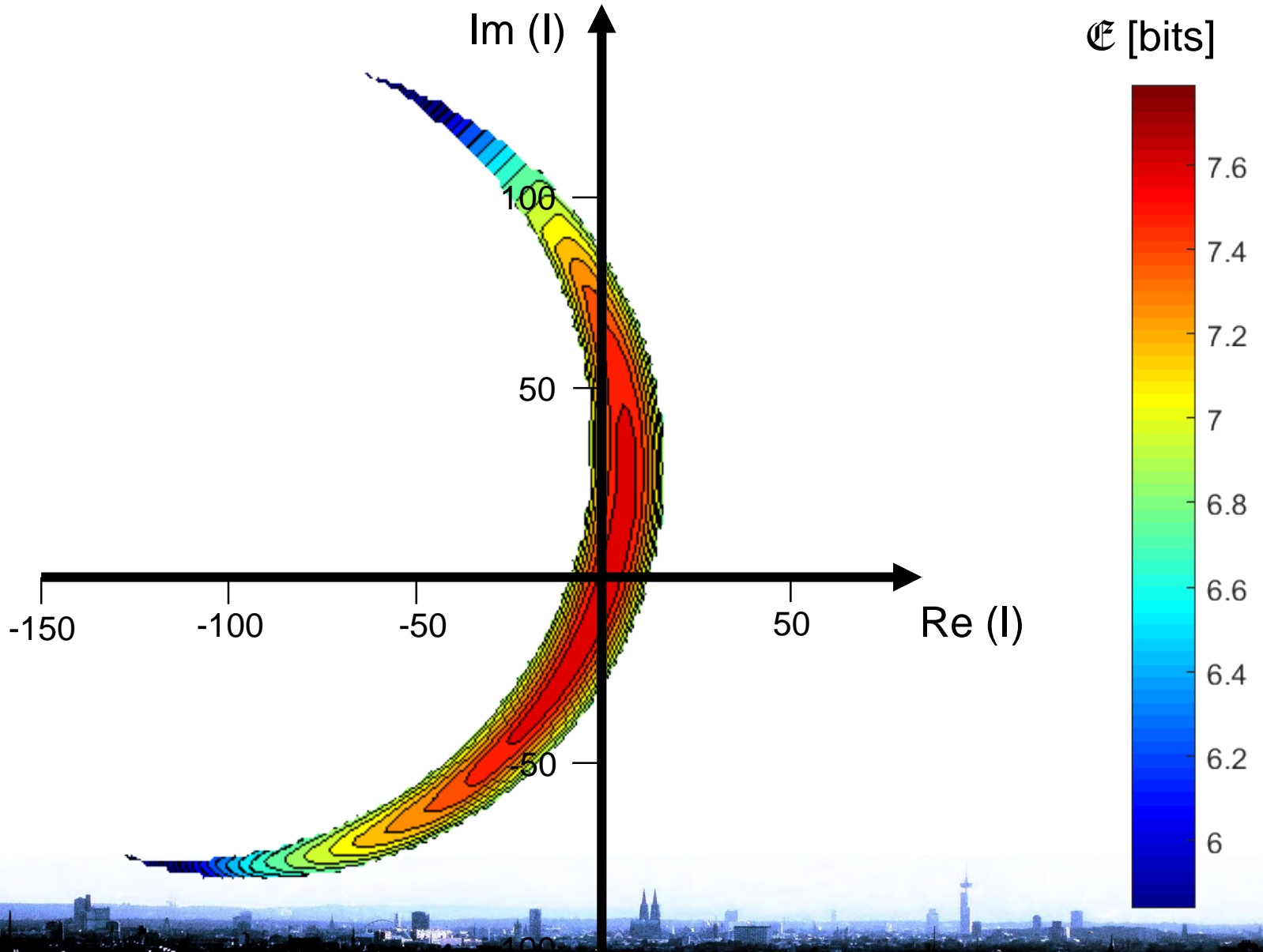
System limits



Application of Empowerment



Application of 10-step-Empowerment



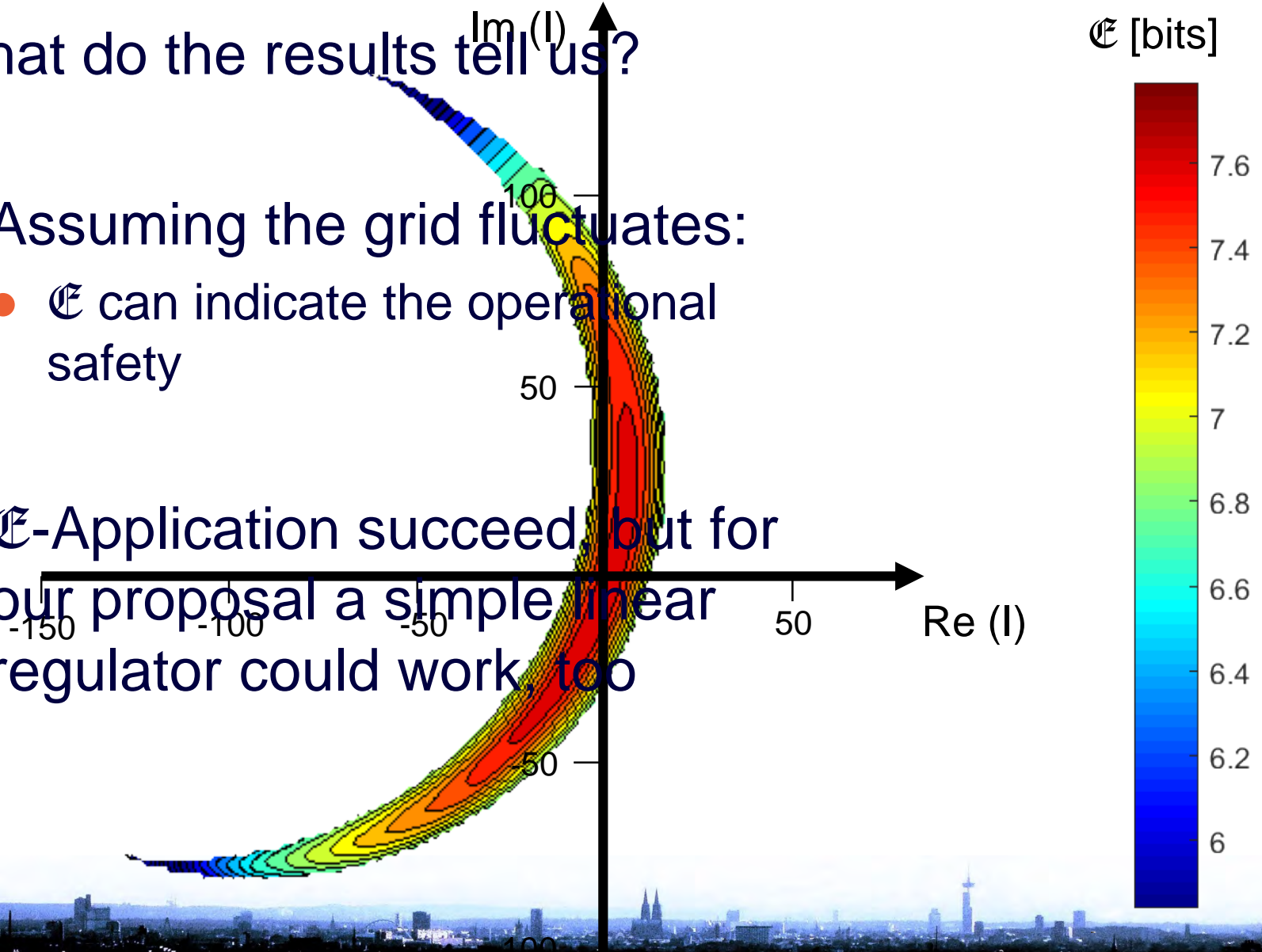
Conclusion

What do the results tell us?

■ Assuming the grid fluctuates:

- \mathcal{E} can indicate the operational safety

■ \mathcal{E} -Application succeed, but for our proposal a simple linear regulator could work, too



Further research areas and applications:

- Local optimization with blurred limits
 - Probability distribution for Actions of the agent
- Self-organization [7]
 - Smart-Grid-Agents (Generators, storages and adjustable loads): How to implement Empowerment in a dynamic world?
- Optimization of multi-variable Problems
 - Find optimal operation point of coupling of the energy sectors electricity, heat, gas and mobility
- Optimization of problems with competing goals
 - Smart provision of balancing power





Thank you for your attention!

Do you have any more ideas for an application of
Empowerment?



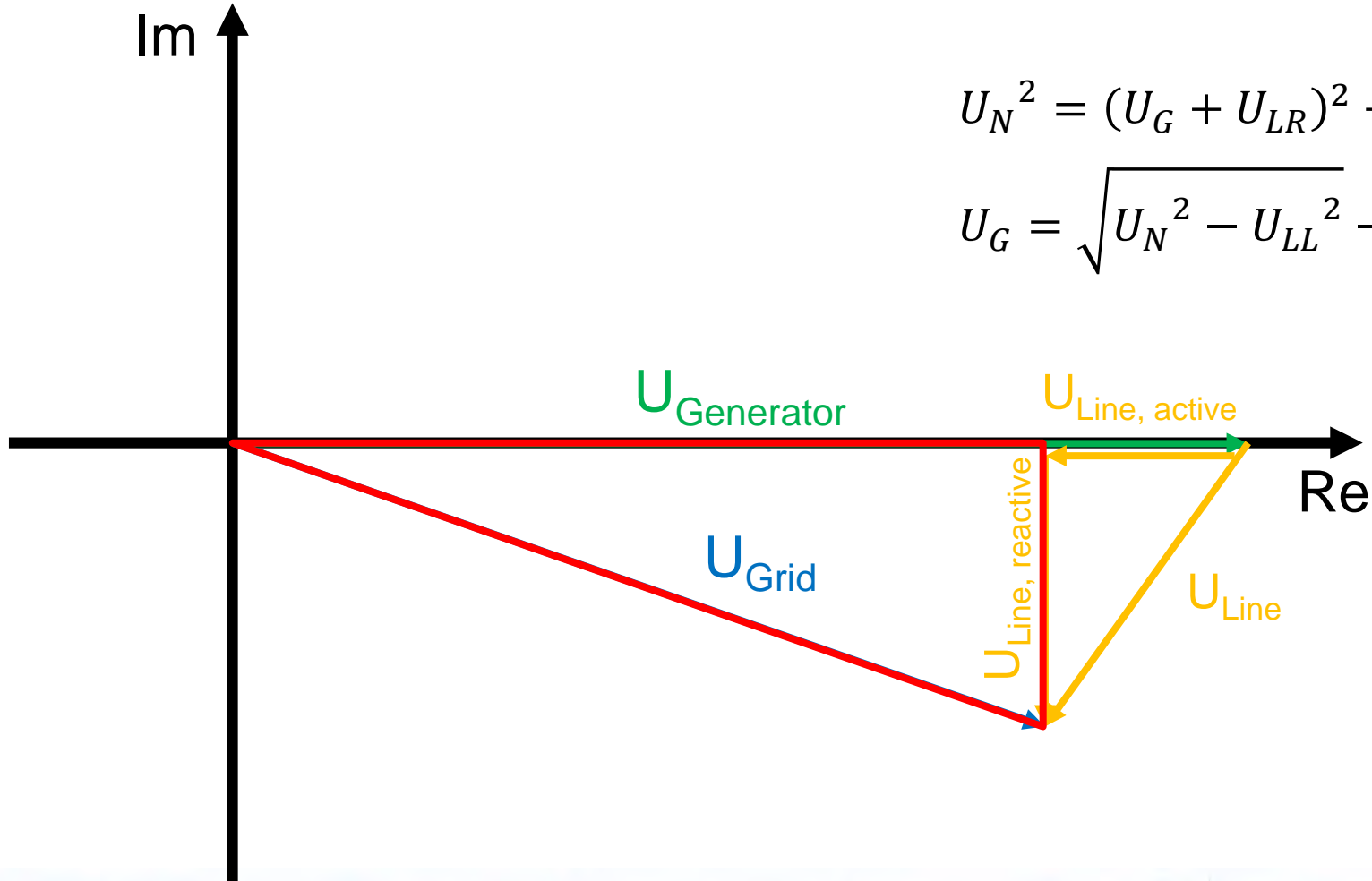
References

- [1] Wikipedia, “Kaffernbüffel – Fressfeinde und Feindverhalten” [Online] Available: https://upload.wikimedia.org/wikipedia/commons/5/50/Lions_vs_Cape_Buffalo.jpg [Accessed: 01.06.2016]
- [2] C. Salge, G. Glackin, D. Polani, “Empowerment – An introduction”, University of Hertfordshire, 2013
- [3] Wikipedia, “Entropy (information theory)” [Online] Available: https://upload.wikimedia.org/wikipedia/commons/d/d4/Entropy_flip_2_coins.jpg [Accessed: 01.06.2016]
- [4] A. S. Klyubin, D. Polani, C. L. Nehaniv, “All Else Being Equal Be Empowered”, University of Hertfordshire, 2005
- [5] E. Waffenschmidt, “Electric grids - Lecture notes”, 2014
- [6] E. Waffenschmidt, “Decentralized structures of electric grids - Lecture notes”, 2015
- [7] P. Capdepuy, “Informational principles of Perception-action loops and collective behaviours”, doctoral thesis, University of Hertfordshire, 2010



Annex: Power factor adaption

■ Voltages in polar diagram

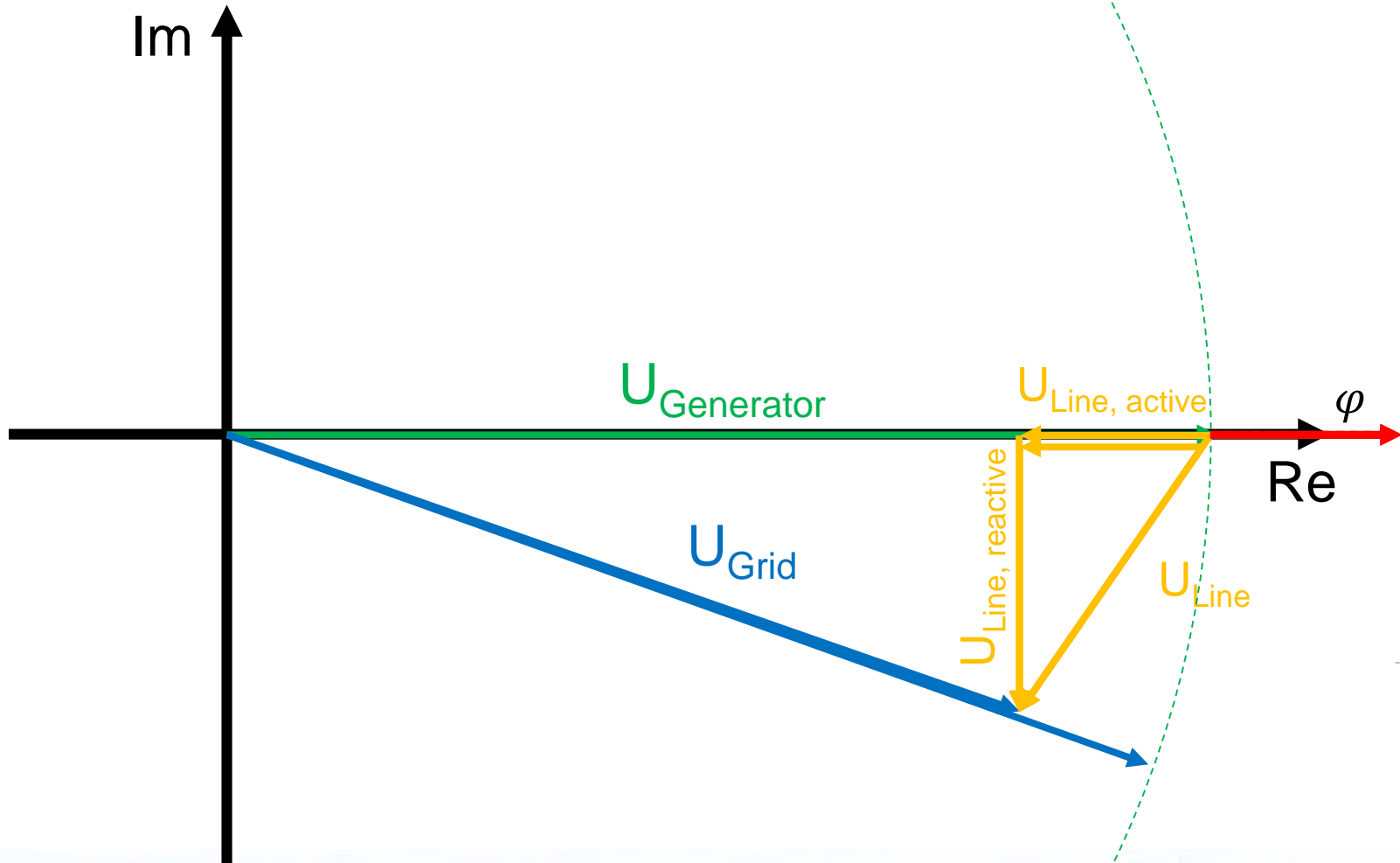


[5]



Annex: Power factor adaption

■ Voltages in polar diagram



[5]

Annex: Power factor adaption

